A Distributed Science Mission Testbed

Completed Technology Project (2016 - 2017)



Project Introduction

The technology required for distributed spacecraft missions (DSM) is currently hamstrung by the lack of a realistic six-degree-of-freedom (DOF) testing platform. A spacecraft emulator using autonomous rotorcraft provides this capability with minimum investment. Modifying commercially available rotorcraft hardware and applying customized attitude and position control algorithms will result in a space-like testing environment for formation flying, astrometric alignment, and other DSM applications.

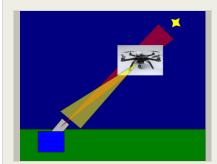
The largest roadblock to advancing distributed spacecraft mission (DSM) technology is the difficulty inherent in demonstrating these concepts in a relevant environment. The complications and expenses required by space-bound technology demonstrations impose onerous costs on budding technologies. Developing an inexpensive test platform that is dynamically similar to the space environment provides an accelerator for a wide range of DSM concepts relevant to all of Goddard's science communities. For example, heliophysics and astrophysics scientists can test coronagraph and virtual telescope concepts like CANYVAL-X, while Earth science principal investigators (PI) can test formations such as MMS or the proposed BOWTIE concept.

Anticipated Benefits

Some future NASA mission concepts rely on the use of distributed systems to make a coordinated science observations. To understand the complexities of distributed systems, a 6 degree of freedom platform would be useful.

Primary U.S. Work Locations and Key Partners





Concept of Operation showing how to use a rotorcraft to demonstrate a distributed spacecraft mission

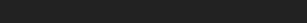
Table of Contents

Project Introduction	1
Anticipated Benefits	1
Primary U.S. Work Locations	
and Key Partners	1
Project Transitions	2
Organizational Responsibility	2
Project Management	2
Technology Maturity (TRL)	2
Images	3
Project Website:	3
Technology Areas	3
Target Destination	3



Center Independent Research & Development: GSFC IRAD

A Distributed Science Mission Testbed





Completed Technology Project (2016 - 2017)

Organizations Performing Work	Role	Туре	Location
☆Goddard Space Flight Center(GSFC)	Lead	NASA	Greenbelt,
	Organization	Center	Maryland

Primary U.S. Work Locations

Maryland

Project Transitions



October 2016: Project Start



September 2017: Closed out

Closeout Summary: The purpose of the Goddard Space Flight Center's Internal Research and Development (IRAD) program is to support new technology develo pment and to address scientific challenges. Each year, Principal Investigators (P Is) submit IRAD proposals and compete for funding for their development projec ts. Goddard's IRAD program supports eight Lines of Business: Astrophysics; Co mmunications and Navigation; Cross-Cutting Technology and Capabilities; Earth Science; Heliophysics; Planetary Science; Science Small Satellites Technology; a nd Suborbital Platforms and Range Services. Task progress is evaluated twice a y ear at the Mid-term IRAD review and the end of the year. When the funding peri od has ended, the PIs compete again for IRAD funding or seek new sources of d evelopment and research funding or agree to external partnerships and collabor ations. In some cases, when the development work has reached the appropriat e Technology Readiness Level (TRL) level, the product is integrated into an actu al NASA mission or used to support other government agencies. The technology may also be licensed out to the industry. The completion of a project does not ne cessarily indicate that the development work has stopped. The work could pote ntially continue in the future as a follow-on IRAD; or used in collaboration or par tnership with Academia, Industry and other Government Agencies. If you are int erested in partnering with NASA, see the TechPort Partnerships documentation a vailable on the TechPort Help tab. http://techport.nasa.gov/help

Organizational Responsibility

Responsible Mission Directorate:

Mission Support Directorate (MSD)

Lead Center / Facility:

Goddard Space Flight Center (GSFC)

Responsible Program:

Center Independent Research & Development: GSFC IRAD

Project Management

Program Manager:

Peter M Hughes

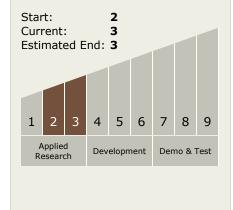
Project Managers:

Jason W Mitchell Michael A Johnson

Principal Investigator:

Neeray Shah

Technology Maturity (TRL)



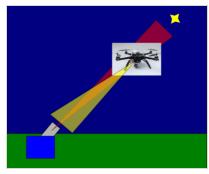


A Distributed Science Mission Testbed

Completed Technology Project (2016 - 2017)



Images



DSM Rotorcraft Test ConceptConcept of Operation showing how to use a rotorcraft to demonstrate a distributed spacecraft mission (https://techport.nasa.gov/imag

Project Website:

e/26366)

http://aetd.gsfc.nasa.gov/

Technology Areas

Primary:

 TX17 Guidance, Navigation, and Control (GN&C)
 TX17.5 GN&C Systems Engineering Technologies
 TX17.5.4 GN&C Ground Testbeds/Test Facilities

Other/Cross-cutting:

- TX17 Guidance, Navigation, and Control (GN&C)

 — TX17.5 GN&C Systems
 - TX17.5 GN&C Systems Engineering Technologies
 - └─ TX17.5.1 GN&C System

 Architectures,

 Requirements and
 Specifications
 - └─ TX17.5.3 GN&C

 Verification & Validation

 Tools & Techniques

Target Destination

Foundational Knowledge

